

# Von Neumann's **Other** Entropy

—observational entropy, coarse-grained states, and irretractability—

*ovvero*

“Of Entropies, Paradoxes, Observers”



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The Observational Entropy Appreciation Club  
([www.observationalentropy.com](http://www.observationalentropy.com))

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# Enter the Entropy

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## von Neumann's entropy

For  $\varrho = \sum_{x=1}^d \lambda_x |\varphi_x\rangle\langle\varphi_x|$   $d$ -dimensional density matrix ( $\lambda_x \geq 0$ ,  $\sum_x \lambda_x = 1$ ),

$$S(\varrho) := -\text{Tr}[\varrho \log \varrho] = -\sum_{x=1}^d \lambda_x \log \lambda_x$$

with the convention  $0 \log 0 := 0$ .

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Unfortunately though:

*“The expressions for entropy given by the author [previously] are not applicable here in the way they were intended, as they were computed from the perspective of an observer who can carry out all measurements that are possible in principle—i.e., regardless of whether they are **macroscopic** [or not].”*

von Neumann, 1929; transl. available in arXiv:1003.2133

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in formula:

### Theorem (least uncertainty)

For  $\rho$  density matrix,  $\text{onb} = \{|\phi_i\rangle\}_i$  orthonormal basis, and  $p_i = \langle \phi_i | \rho | \phi_i \rangle$ ,

$$S(\rho) = \min_{\text{onb}} \left[ - \sum_i p_i \log p_i \right] .$$

For a more general result, see [M. Dall’Arno and F.B., IEEE TIT, 65(4), 2018].

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# Enter the Paradox

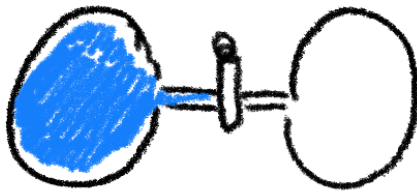
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*“Although our entropy expression, as we saw, is completely analogous to the classical entropy, it is still surprising that **it is invariant in the normal [Hamiltonian] evolution in time of the system,** and only increases with measurements—in the classical theory (where the measurements in general played no role) it increased as a rule even with the ordinary mechanical evolution in time of the system. It is therefore necessary to clear up this apparently **paradoxical situation.**”*

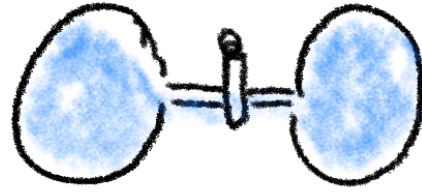
von Neumann, book (Math. Found. QM), 1932 (transl. 1955)

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## free expansion of an ideal gas



$$P_i, V_i, T_i$$



$$\frac{P_i}{2}, 2V_i, T_i$$

$$\Delta S(\text{universe}) = nR \ln 2 > 0$$

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## invariance of von Neumann entropy

Instead,

### Theorem

For any unitary operator  $U$ ,

$$S(\rho) = S(U\rho U^\dagger),$$

for all density matrices  $\rho$ .

$\implies$  the entropy increasing during a free expansion **cannot be the von Neumann entropy**

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## von Neumann's insight (inspired by Szilard's)

*“For a classical observer, who knows all coordinates and momenta, the entropy is constant. [...]*

*The time variations of the entropy are then based on the fact that **the observer does not know everything**—that he cannot find out (measure) everything which is measurable in principle.”*

von Neumann, 1932 (transl. 1955)

# Enter the Observer

## von Neumann's proposal: macroscopic entropy

For

- $\varrho$  density matrix,
- $\mathfrak{P} = \{\Pi_i\}_i$  orthogonal resolution of identity,
- $p_i = \text{Tr}[\varrho \Pi_i]$ ,
- $\Omega_i := \text{Tr}[\Pi_i]$ ,

$$S_{\mathfrak{P}}(\varrho) := - \sum_i p_i \log \frac{p_i}{\Omega_i}$$

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## modern generalization: observational entropy

For

- $\varrho$  density matrix,
- $\mathbf{P} = \{P_i\}_i$  POVM (i.e.,  $P_i \geq 0$ ,  $\sum_i P_i = \mathbb{1}$ ),
- $p_i = \text{Tr}[\varrho P_i]$ ,
- $V_i := \text{Tr}[P_i]$ ,

$$S_{\mathbf{P}}(\varrho) := - \sum_i p_i \log \frac{p_i}{V_i}$$

References:

- ① D. Šafránek, J.M. Deutsch, A. Aguirre. *Phys. Rev. A* **99**, 012103 (2019)
- ② D. Šafránek, A. Aguirre, J. Schindler, J. M. Deutsch. *Found. Phys.* **51**, 101 (2021)

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## “observational” = “of the observer”

- von Neumann defines a **macro-observer** as a collection of **simultaneously measurable quantities**  $\{\mathbf{Q}_1, \mathbf{Q}_2, \dots, \mathbf{Q}_n, \dots\}$ , where  $\mathbf{Q}_n = \{Q_{x|n}\}_x$  are POVMs
- $\implies$  there exists one “mother” POVM  $\mathbf{P} = \{P_i\}_i$  and a stochastic processing (i.e., cond. prob.)  $\mu$  such that

$$Q_{x|n} = \sum_i \mu(x|n, i) P_i, \quad \forall x, n$$

- $\implies$  “a macro-observer” := “a POVM”—from which all macroscopic measurements (i.e., coarse-grainings) can be simultaneously inferred by stochastic post-processing

## Mathematical properties

from arXiv:2209.03803



# Umegaki's relative entropy

## Definition

For density matrices  $\varrho, \sigma$ ,

$$D(\varrho\|\sigma) := \begin{cases} \text{Tr}[\varrho(\log \varrho - \log \sigma)] , & \text{if } \text{supp } \varrho \subseteq \text{supp } \sigma , \\ +\infty , & \text{otherwise} \end{cases}$$

Useful properties:

- $D(A\|B) \geq 0$
- $S(\varrho) = \log d - D(\varrho\|u)$  where  $u := d^{-1}\mathbb{1}$
- **monotonicity:**  $D(\varrho\|\sigma) \geq D(\mathcal{E}(\varrho)\|\mathcal{E}(\sigma))$  for all channels (i.e., CPTP linear maps)  $\mathcal{E}$  and all states  $\varrho, \sigma$

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# a bound on the observational entropy

## Theorem

For any state  $\varrho$  and any POVM  $\mathbf{P} = \{P_i\}_i$

$$S(\varrho) \leq S_{\mathbf{P}}(\varrho) .$$

## Proof.

Given a POVM  $\mathbf{P}$ , by defining the corresponding CPTP linear map  $\mathcal{P}(\bullet) := \sum_i \text{Tr}[P_i \bullet] |i\rangle\langle i|$ , we have ( $u = d^{-1}\mathbb{1}$ )

$$S_{\mathbf{P}}(\varrho) - S(\varrho) = D(\varrho\|u) - D(\mathcal{P}(\varrho)\|\mathcal{P}(u)) ,$$

which is non-negative due to the monotonicity property of the Umegaki quantum relative entropy. □

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## Petz's theorem

In general,  $D(\varrho\|\sigma) \geq D(\mathcal{E}(\varrho)\|\mathcal{E}(\sigma))$ .

**Question:** for which triples  $(\varrho, \sigma, \mathcal{E})$  does the equality  $D(\varrho\|\sigma) = D(\mathcal{E}(\varrho)\|\mathcal{E}(\sigma))$  hold?

**Petz (1986,1988)**

**Answer:** if and only if the “transpose channel”, i.e.,

$$\tilde{\mathcal{E}}_\sigma(\bullet) := \sqrt{\sigma} \mathcal{E}^\dagger \left[ \frac{1}{\sqrt{\mathcal{E}(\sigma)}} \bullet \frac{1}{\sqrt{\mathcal{E}(\sigma)}} \right] \sqrt{\sigma}$$

satisfies  $\tilde{\mathcal{E}}_\sigma \circ \mathcal{E}(\varrho) = \varrho$ . (The other equality  $\tilde{\mathcal{E}}_\sigma \circ \mathcal{E}(\sigma) = \sigma$  is satisfied *by construction*.)

**Remark.** Notice that  $\tilde{\mathcal{E}}_\sigma$  in general is *not* the linear inverse of  $\mathcal{E}$ —rather, it is related with the idea of *statistical retrodiction* (more on this later).

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## consequences for observational entropy

### Theorem

$$S(\varrho) = S_{\mathbf{P}}(\varrho) \iff \varrho = \sum_i \text{Tr}[\varrho P_i] \frac{P_i}{V_i}.$$

We call such a state *fully observable* or *macroscopic* (w.r.t.  $\mathbf{P}$ ).

### Proof.

This is a direct consequence of Petz's transpose map theorem:

$S_{\mathbf{P}}(\varrho) - S(\varrho) = D(\varrho\|u) - D(\mathcal{P}(\varrho)\|\mathcal{P}(u)) = 0$  if and only if  $\varrho = \tilde{\mathcal{P}}_u(\mathcal{P}(\varrho))$ . By direct inspection,  $\tilde{\mathcal{P}}_u(\mathcal{P}(\varrho)) = \sum_i \text{Tr}[\varrho P_i] P_i/V_i$ .  $\square$

**Remark.** For any POVM  $\mathbf{P}$ , at least one fully observable state  $\varrho$  exists, e.g., the uniform  $u$ .

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# The resolution of the paradox

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- start at  $t = t_0$  from a **fully observable state**, i.e., such that  $S_{\mathbf{P}}(\varrho^{t_0}) = S(\varrho^{t_0})$
- the system undergoes **unitary evolution**, i.e.,  $\varrho^{t_0} \mapsto \varrho^{t_1} = U \varrho^{t_0} U^\dagger$ ; then,

$$\begin{aligned} S_{\mathbf{P}}(\varrho^{t_1}) &\equiv - \sum_i \text{Tr}[P_i (U \varrho^{t_0} U^\dagger)] \log \frac{\text{Tr}[P_i (U \varrho^{t_0} U^\dagger)]}{\text{Tr}[P_i]} \\ &= - \sum_i \text{Tr}[(U^\dagger P_i U) \varrho^{t_0}] \log \frac{\text{Tr}[(U^\dagger P_i U) \varrho^{t_0}]}{\text{Tr}[U^\dagger P_i U]} \equiv S_{U^\dagger \mathbf{P} U}(\varrho^{t_0}) \end{aligned}$$

- hence, in general,  $S_{\mathbf{P}}(\varrho^{t_1}) \equiv S_{U^\dagger \mathbf{P} U}(\varrho^{t_0}) \geq S(\varrho^{t_0}) \equiv S_{\mathbf{P}}(\varrho^{t_0})$ , and the following are equivalent:
  - ▶  $S_{\mathbf{P}}(\varrho^{t_1}) = S_{\mathbf{P}}(\varrho^{t_0})$ , i.e., the observational entropy does not increase
  - ▶  $S_{U^\dagger \mathbf{P} U}(\varrho^{t_0}) = S(\varrho^{t_0})$
  - ▶  $\varrho^{t_0} = \sum_i \text{Tr}[(U^\dagger P_i U) \varrho^{t_0}] \frac{U^\dagger P_i U}{V_i}$
  - ▶  $\varrho^{t_1} = \sum_i \text{Tr}[P_i \varrho^{t_1}] \frac{P_i}{V_i}$
  - ▶  $S_{\mathbf{P}}(\varrho^{t_1}) = S(\varrho^{t_1})$ , i.e.,  $\varrho^{t_1}$  is fully observable
- in words: the observational entropy of a fully observable state evolving unitarily cannot decrease, and **it remains constant if and only if the state remains fully observable**

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# Generalization to finite differences

## triangle equality for observational entropy

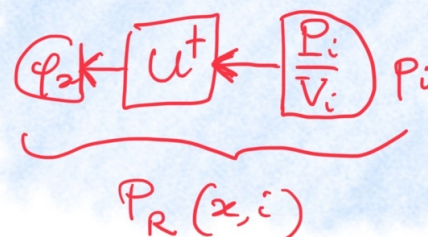
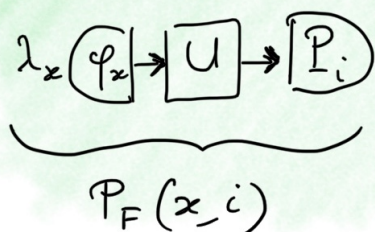
### Theorem

Given a  $d$ -dimensional system, a density matrix  $\rho$  with diagonalization  $\{\lambda_x, |\varphi_x\rangle\}_{x=1}^d$ , a unitary operator  $U$ , and a POVM  $\mathbf{P} = \{P_i\}_i$ , let us define two joint probability distributions:

$$P_F(x, i) := \lambda_x \operatorname{Tr}[U|\varphi_x\rangle\langle\varphi_x|U^\dagger P_i] \quad , \quad P_R(x, i) := p_i \operatorname{Tr}\left[|\varphi_x\rangle\langle\varphi_x| \frac{U^\dagger P_i U}{V_i}\right] .$$

Then,

$$S_{\mathbf{P}}(U\rho U^\dagger) - S(\rho) = D(P_F \| P_R) .$$



## interpretation: prediction and retrodiction

- start from  $P_F(x, i) = \lambda_x \langle \varphi_x | U^\dagger P_i U | \varphi_x \rangle =: \lambda_x \pi_F(i|x)$
- notice that  $\sum_i P_F(x, i) = \lambda_x$  and  $\sum_x P_F(x, i) = \text{Tr}[U \rho U^\dagger P_i] = p_i$
- write this as  $\lambda \xrightarrow{\pi} \pi[\lambda] \equiv p$
- take now  $P_R(x, i) = p_i \langle \varphi_x | \frac{U^\dagger P_i U}{V_i} | \varphi_x \rangle =: p_i \pi_R(x|i)$
- notice that  $\pi_R(x|i) = \frac{\langle \varphi_x | U^\dagger P_i U | \varphi_x \rangle}{\sum_x \langle \varphi_x | U^\dagger P_i U | \varphi_x \rangle} = \frac{d^{-1} \langle \varphi_x | U^\dagger P_i U | \varphi_x \rangle}{\sum_x d^{-1} \langle \varphi_x | U^\dagger P_i U | \varphi_x \rangle} = \frac{u_x \pi_F(i|x)}{\sum_x u_x \pi_F(i|x)}$
- hence  $\pi_R(x|i)$  is the Bayesian inverse  $\tilde{\pi}_u$  of the process  $u \xrightarrow{\pi} \pi[u]$

### in the language of Jeffrey's "probability kinematics"

- $P_F$  corresponds to the **prediction**  $\lambda \xrightarrow{\pi} \bullet$ : the inference about  $i$
- $P_R$  corresponds to the **retrodiction**  $\bullet \xleftarrow{\tilde{\pi}_u} p$ : the inference about  $x$  that a **completely uninformed Bayesian agent** would do, if given information about  $i$  in the form of the probability distribution  $p$ .

The equality  $S_{\mathbf{P}}(U \rho U^\dagger) = S(\rho)$  occurs **if and only if** predictor and retrodicator agree.

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## Watanabe's contention



*"The phenomenological oneway-ness of temporal developments in physics is due to **irretrodictability**, and not due to irreversibility."*

Satosi Watanabe (1965)

The second law of thermodynamics is not about the "arrow of time", but about the **arrow of inference**.

- F.B. and V. Scarani, *Fluctuation relations from Bayesian retrodiction*, PRE (2021)
- C.C. Aw, F.B., and V. Scarani, *Fluctuation theorems with retrodiction rather than reverse processes*, AVS Quantum Science (2021)

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## a bound for quantum retrodiction

Can we say something about the **quantum** process itself, i.e., independently of any particular diagonalization of  $\rho$ ?

### Theorem

Given a density matrix  $\rho$ , a unitary operator  $U$ , and a POVM  $\mathbf{P} = \{P_i\}_i$ ,

$$S_{\mathbf{P}}(U\rho U^\dagger) - S(\rho) \geq D(\rho \parallel \tilde{\rho}_r),$$

where  $\tilde{\rho}_r := \sum_i \text{Tr}[U\rho U^\dagger P_i] \frac{U^\dagger P_i U}{V_i}$  is the state **retrodicted by the later observer**.

**Remark.** Notice that in general  $[\rho, \tilde{\rho}_r] \neq 0$ .

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## Conclusions

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## take-home messages

When the use of von Neumann entropy in thermodynamics is problematic, try consider **observational entropy (OE)** instead, because:

- 1 **von Neumann told you so!** OE has a fully **operational/inferential definition**
- 2 OE describes thermodynamic scenarios avoiding **interpretational paradoxes**
- 3 OE fits nicely within recent developments in **quantum mathematical statistics** (e.g., approximate Petz recovery)
- 4 OE suggests a natural candidate for **quantum retrodiction**

**THE END: THANK YOU!**